

## **AMENDMENTS TO THE SPECIFICATION**

Please replace Paragraph **[0030]** with the following paragraph rewritten in amendment format:

**[0030]** Figures 23a-23i and 24 depict visual elements shown on a control panel of the present invention.

Please replace Paragraph **[0066]** with the following paragraph rewritten in amendment format:

**[0066]** Figure 22 represents a flow chart of the operation of the system of the present invention. The process begins with query block 120 which queries the operator as to the required stack configuration. Associated with each of these stack configurations is a predetermined number of robotic arm movement patterns as well as pallet indexing and sod spacing information. After completing the query, the system displays a work screen in process block 122. The work screen contains a pictorial representation of the skid while it is being loaded with sod. In this regard, the operator can check the status of a skid by watching the screen (see Figures 23a-23i). The system begins skid loading by indexing the skid 124 into its proper orientation. Based upon which stack configuration is chosen by the operator, the roll count per row for a given layer is sod is retrieved from a memory location 126. Further retrieved from memory 128 and set 130 is the spacing of the gripper modules of the head 128. The robotic arm's path is set in operation block 132.